

MODULE-4

Introduction

Let V and W be vector spaces and let T be a function from V to W . The V is called the domain of T and W the codomain of T .

Let $v \in V$ and $w \in W$ s.t. $T(v) = w$.

Then w is called the image of v under T .

The set of all images of vectors in V is called the range of T .

For a given $w \in W$ the set of all v in V such that $T(v) = w$ is called the preimage of w .

Problems

1. Let $v = (v_1, v_2) \in \mathbb{R}^2$. If $T: V \rightarrow W$ is defined as

$$T(v_1, v_2) = (v_1 + v_2, 2v_2)$$

1. Find the image of $v = (1, -3)$

2. Find the image of $v = (0, 0)$

3. Find the preimage of $w = (1, 3)$.

Ans: $T(v_1, v_2) = (v_1 + v_2, 2v_2)$

1) $T(1, -3) = (1 + (-3), 2 \times (-3)) = (-2, -6)$

2) $T(0, 0) = (0 + 0, 2 \times 0) = (0, 0)$

3) To find the preimage of $w = (1, 3)$ consider set of all (v_1, v_2) such that $T(v_1, v_2) = (1, 3)$

$$\Rightarrow (v_1 + v_2, 2v_2) = (1, 3)$$

$$\Rightarrow v_1 + v_2 = 1, \quad 2v_2 = 3$$

$$\Rightarrow v_2 = \frac{3}{2}$$

$$v_1 + v_2 = 1 \Rightarrow v_1 + \frac{3}{2} = 1$$

$$\Rightarrow v_1 = 1 - \frac{3}{2} = \frac{-1}{2}$$

\therefore Preimage of $w = (1, 3)$ is $(\frac{-1}{2}, \frac{3}{2})$

Q. Let $v = (v_1, v_2, v_3) \in \mathbb{R}^3$. If $T: V \rightarrow W$ is defined as

$$T(v_1, v_2, v_3) = (2v_1 + v_2, 2v_2 - 3v_1, v_1 - v_3)$$

a) Find the image of $v = (-4, 5, 1)$

b) Find the preimage of $w = (4, 1, -1)$

Ans: $T(v_1, v_2, v_3) = (2v_1 + v_2, 2v_2 - 3v_1, v_1 - v_3)$

a) $T(-4, 5, 1) = (2 \times -4 + 5, 2 \times 5 - 3 \times -4, -4 - 1)$

$$= \underline{\underline{(-3, 29, -5)}}$$

b) To find pre image of $w = (4, 1, -1)$ consider set

of all (v_1, v_2, v_3) s.t. $T(v_1, v_2, v_3) = (4, 1, -1)$

$$\Rightarrow (2v_1 + v_2, 2v_2 - 3v_1, v_1 - v_3) = (4, 1, -1)$$

$$\Rightarrow 2v_1 + v_2 = 4$$

$$2v_2 - 3v_1 = 1 \Rightarrow -3v_1 + 2v_2 = 1$$

$$v_1 - v_3 = -1$$

$$\therefore Ax = B \Rightarrow \begin{bmatrix} 2 & 1 & 0 \\ -3 & 2 & 0 \\ 1 & 0 & -1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 4 \\ 1 \\ -1 \end{bmatrix}$$

Augmented matrix = ~~27~~ $\begin{bmatrix} 2 & 1 & 0 & 4 \\ -3 & 2 & 0 & 1 \\ 1 & 0 & -1 & -1 \end{bmatrix} R_1 \rightarrow \frac{R_1}{2}$

$$\sim \begin{bmatrix} 1 & \frac{1}{2} & 0 & 2 \\ -3 & 2 & 0 & 1 \\ 1 & 0 & -1 & -1 \end{bmatrix} \begin{array}{l} R_2 \rightarrow R_2 + 3R_1 \\ R_3 \rightarrow R_3 - R_1 \end{array}$$

$$\sim \begin{bmatrix} 1 & \frac{1}{2} & 0 & 2 \\ 0 & \frac{7}{2} & 0 & 7 \\ 0 & -\frac{1}{2} & -1 & -3 \end{bmatrix} R_2 \rightarrow R_2 \times \frac{2}{7}$$

$$\sim \begin{bmatrix} 1 & \frac{1}{2} & 0 & 2 \\ 0 & 1 & 0 & 2 \\ 0 & -\frac{1}{2} & -1 & -3 \end{bmatrix} R_3 \rightarrow R_3 + \frac{1}{2} R_2$$

$$\sim \begin{bmatrix} 1 & \frac{1}{2} & 0 & 2 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & -1 & -2 \end{bmatrix} R_3 \rightarrow \frac{R_3}{-1}$$

$$\sim \begin{bmatrix} 1 & \frac{1}{2} & 0 & 2 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 2 \end{bmatrix}$$

$$\therefore V_1 + \frac{1}{2} V_2 = 2$$

$$V_2 = 2$$

$$V_3 = 2$$

$$\therefore V_1 + \frac{1}{2} \cdot 2 = 2 \Rightarrow V_1 = 2 - 1 = 1$$

\therefore Pre image of $w = (4, 1, -1)$ is $(1, 2, 2)$

Linear Transformation

Let V and W be vector spaces. The function $T: V \rightarrow W$ is a linear transformation of V into W when the following two properties holds for all $u, v \in V$ and for any scalar c

$$1) T(u+v) = T(u) + T(v)$$

$$2) T(cu) = cT(u).$$

Linear Operators

A linear transformation $T: V \rightarrow V$ from a vector space V onto itself is called a linear operator.

Problems

1. Show that the function $T(v_1, v_2) = (v_1 + v_2, v_1 - 2v_2)$ is a linear transformation from \mathbb{R}^2 into \mathbb{R}^2 .

Ans: ~~If~~ Let $u = (u_1, u_2)$, $v = (v_1, v_2) \in \mathbb{R}^2$ and let c be any real number.

$$\begin{aligned} T(u+v) &= T(u_1 + v_1, u_2 + v_2) \\ &= (u_1 + v_1 + u_2 + v_2, u_1 + v_1 - 2(u_2 + v_2)) \\ &= (u_1 + u_2 + v_1 + v_2, u_1 - 2u_2 + v_1 - 2v_2) \\ &= (u_1 + u_2, u_1 - 2u_2) + (v_1 + v_2, v_1 - 2v_2) \\ &= T(u, u_2) + T(v_1, v_2) \\ &= T(u) + T(v) \end{aligned}$$

$$\begin{aligned} T(cu) &= T(cu_1, cu_2) \\ &= T(cu_1, cu_2) \\ &= (cu_1 + cu_2, cu_1 - 2cu_2) \\ &= c(u_1 + u_2, u_1 - 2u_2) \\ &= cT(u, u_2) = cT(u) \end{aligned}$$

$\therefore T$ is a linear transformation.

2. Determine whether the function $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ defined by $T(x, y) = (x, 1)$ is a linear transformation.

Ans: Let $u = (u_1, u_2)$ and $v = (v_1, v_2) \in \mathbb{R}^2$.

$$\begin{aligned} T(u+v) &= T((u_1, u_2) + (v_1, v_2)) \\ &= T(u_1+v_1, u_2+v_2) \\ &= (u_1+v_1, 1) \end{aligned}$$

$$\begin{aligned} T(u) + T(v) &= T(u_1, u_2) + T(v_1, v_2) \\ &= (u_1, 1) + (v_1, 1) \\ &= (u_1+v_1, 2) \end{aligned}$$

$$\therefore T(u+v) \neq T(u) + T(v).$$

So T is not a linear transformation.

3. Determine whether the function $T: \mathbb{R}^2 \rightarrow \mathbb{R}^3$ defined by $T(x, y) = (x^2, xy, y^2)$ is a linear transformation.

Ans: Let $u = (u_1, u_2)$, $v = (v_1, v_2) \in \mathbb{R}^2$

$$\begin{aligned} T(u+v) &= T((u_1, u_2) + (v_1, v_2)) \\ &= T(u_1+v_1, u_2+v_2) \\ &= ((u_1+v_1)^2, (u_1+v_1)(u_2+v_2), (u_2+v_2)^2) \end{aligned}$$

$$\begin{aligned} T(u) + T(v) &= T(u_1, u_2) + T(v_1, v_2) \\ &= (u_1^2, u_1u_2, u_2^2) + (v_1^2, v_1v_2, v_2^2) \\ &= (u_1^2+v_1^2, u_1u_2+v_1v_2, u_2^2+v_2^2) \end{aligned}$$

$$\therefore T(u+v) \neq T(u) + T(v)$$

So T is not a linear transformation.

4. Check whether $T: M_{2,2} \rightarrow \mathbb{R}$ defined by

$T(A) = a+b+c+d$ where $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ is a linear transformation.

Ans: Let $A_1 = \begin{bmatrix} a_1 & b_1 \\ c_1 & d_1 \end{bmatrix}$, $A_2 = \begin{bmatrix} a_2 & b_2 \\ c_2 & d_2 \end{bmatrix} \in M_{2,2}$

$$\begin{aligned} T(A_1 + A_2) &= T\left(\begin{bmatrix} a_1 & b_1 \\ c_1 & d_1 \end{bmatrix} + \begin{bmatrix} a_2 & b_2 \\ c_2 & d_2 \end{bmatrix}\right) \\ &= T\left(\begin{bmatrix} a_1 + a_2 & b_1 + b_2 \\ c_1 + c_2 & d_1 + d_2 \end{bmatrix}\right) \\ &= a_1 + a_2 + b_1 + b_2 + c_1 + c_2 + d_1 + d_2 \end{aligned}$$

$$\begin{aligned} T(A_1) + T(A_2) &= T\begin{bmatrix} a_1 & b_1 \\ c_1 & d_1 \end{bmatrix} + T\begin{bmatrix} a_2 & b_2 \\ c_2 & d_2 \end{bmatrix} \\ &= a_1 + b_1 + c_1 + d_1 + a_2 + b_2 + c_2 + d_2 \end{aligned}$$

$$\Rightarrow T(A_1 + A_2) = T(A_1) + T(A_2)$$

$$\begin{aligned} T(cA_1) &= T\left(c \begin{bmatrix} a_1 & b_1 \\ c_1 & d_1 \end{bmatrix}\right) \\ &= T\begin{bmatrix} ca_1 & cb_1 \\ cc_1 & cd_1 \end{bmatrix} = ca_1 + cb_1 + cc_1 + cd_1 \end{aligned}$$

$$\begin{aligned} cT(A_1) &= cT\left(\begin{bmatrix} a_1 & b_1 \\ c_1 & d_1 \end{bmatrix}\right) \\ &= c(a_1 + b_1 + c_1 + d_1) = ca_1 + cb_1 + cc_1 + cd_1 \end{aligned}$$

$$\therefore T(cA_1) = cT(A_1)$$

$\therefore T$ is a linear transformation

5. Let $u \in \mathbb{R}^2$ and $v = (1, 1)$. Check whether $T(u) = \text{Proj}_v u$ is a linear transformation from \mathbb{R}^2 to \mathbb{R}^2 .

Ans: $\text{Proj}_v u = \frac{\langle u, v \rangle}{\langle v, v \rangle} v$

$$T(u_1 + u_2) = \text{Proj}_V(u_1 + u_2)$$

$$= \frac{\langle u_1 + u_2, v \rangle}{\langle v, v \rangle} v$$

$$= \left(\frac{\langle u_1, v \rangle}{\langle v, v \rangle} + \frac{\langle u_2, v \rangle}{\langle v, v \rangle} \right) v$$

$$= \frac{\langle u_1, v \rangle}{\langle v, v \rangle} v + \frac{\langle u_2, v \rangle}{\langle v, v \rangle} v$$

$$= \text{Proj}_V u_1 + \text{Proj}_V u_2$$

$$= T(u_1) + T(u_2)$$

$$T(cu) = \text{Proj}_V cu$$

$$= \frac{\langle cu, v \rangle}{\langle v, v \rangle} v$$

$$= c \frac{\langle u, v \rangle}{\langle v, v \rangle} v$$

$$= c \text{Proj}_V u$$

$$= c T(u)$$

$\therefore T$ is a linear transformation.

Note

Let V and W be vector spaces and let T be a linear transformation from V into W , and let

$u, v \in V$. Then

$$1) T(0) = 0$$

$$2) T(-v) = -T(v)$$

$$3) T(u-v) = T(u) - T(v)$$

Problems

Hw 1. Let $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be a linear transformation such that $T(1,0,0) = (3,1,-4)$, $T(0,1,0) = (-1,3,-2)$, $T(0,0,1) = (0,2,1)$. Find $T(1,2,-3)$.

Ans: Expressing the vector $(1,2,-3)$ as a linear combination of the vectors $(1,0,0)$, $(0,1,0)$ and $(0,0,1)$ we have

$$\begin{aligned}(1,2,-3) &= c_1(1,0,0) + c_2(0,1,0) + c_3(0,0,1) \\ &= (c_1, c_2, c_3)\end{aligned}$$

$$\Rightarrow c_1 = 1, c_2 = 2, c_3 = -3$$

$$\therefore (1,2,-3) = 1(1,0,0) + 2(0,1,0) - 3(0,0,1)$$

$$\begin{aligned}\therefore T(1,2,-3) &= 1T(1,0,0) + 2T(0,1,0) - 3T(0,0,1) \\ &= 1(3,1,-4) + 2(-1,3,-2) - 3(0,2,1) \\ &= (3,1,-4) + (-2,6,-4) - (0,6,3) \\ &= \underline{\underline{(1,1,-11)}}\end{aligned}$$

2. Let $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be a linear transformation such that $T(1,1,1) = (2,0,-1)$, $T(0,-1,2) = (-3,2,-1)$, $T(1,0,1) = (1,1,0)$. Find $T(4,2,0)$.

Ans: Expressing the vector $(4,2,0)$ as a linear combination of the vectors $(1,1,1)$, $(0,-1,2)$ and $(1,0,1)$ we have

$$(4,2,0) = c_1(1,1,1) + c_2(0,-1,2) + c_3(1,0,1)$$

$$= (c_1, c_1, c_1) + (0, -c_2, 2c_2) + (c_3, 0, c_3)$$

$$= (c_1 + c_3, c_1 - c_2, c_1 + 2c_2 + c_3)$$

$$\Rightarrow c_1 + c_3 = 4$$

$$c_1 - c_2 = 2$$

$$c_1 + 2c_2 + c_3 = 0$$

Using Gauss elimination method, the augmented

matrix is
$$\begin{bmatrix} 1 & 0 & 1 & 4 \\ 1 & -1 & 0 & 2 \\ 1 & 2 & 1 & 0 \end{bmatrix}$$

$$\begin{array}{l} R_2 \rightarrow R_2 - R_1 \\ R_3 \rightarrow R_3 - R_1 \end{array} \sim \begin{bmatrix} 1 & 0 & 1 & 4 \\ 0 & -1 & -1 & -2 \\ 0 & 2 & 0 & -4 \end{bmatrix}$$

$$R_2 \rightarrow \frac{R_2}{-1} \sim \begin{bmatrix} 1 & 0 & 1 & 4 \\ 0 & 1 & 1 & 2 \\ 0 & 2 & 0 & -4 \end{bmatrix}$$

$$R_3 \rightarrow R_3 - 2R_2 \sim \begin{bmatrix} 1 & 0 & 1 & 4 \\ 0 & 1 & 1 & 2 \\ 0 & 0 & -2 & -8 \end{bmatrix}$$

$$R_3 \rightarrow \frac{R_3}{-2} \sim \begin{bmatrix} 1 & 0 & 1 & 4 \\ 0 & 1 & 1 & 2 \\ 0 & 0 & 1 & 4 \end{bmatrix}$$

$$\therefore c_1 + c_3 = 4$$

$$c_2 + c_3 = 2$$

$$c_3 = 4$$

$$\therefore c_2 + 4 = 2 \Rightarrow c_2 = 2 - 4 = -2$$

$$c_1 + 4 = 4 \Rightarrow c_1 = 4 - 4 = 0$$

$$\therefore (4, 2, 0) = 0(1, 1, 1) - 2(0, -1, 2) + 4(1, 0, 1)$$

$$\therefore T(4, 2, 0) = 0T(1, 1, 1) - 2T(0, -1, 2) + 4T(1, 0, 1)$$

$$\begin{aligned} \Rightarrow T(4, 2, 0) &= 0 - 2(-3, 2, -1) + 4(1, 1, 0) = \\ &= (6, -4, 2) + (4, 4, 0) = \\ &= \underline{\underline{(10, 0, 2)}} \end{aligned}$$

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 Let $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be a linear transformation such that $T(1, 0) = (1, 1)$, $T(0, 1) = (-1, 1)$. Find $T(x, y)$ and hence evaluate $T(1, 4)$ and $T(-2, 1)$.

Ans: Expressing $(x, y) \in \mathbb{R}^2$ as a linear combination of $(1, 0)$ and $(0, 1)$, we have

$$\begin{aligned} (x, y) &= c_1(1, 0) + c_2(0, 1) \\ &= (c_1, 0) + (0, c_2) \\ &= (c_1, c_2) \end{aligned}$$

$$\Rightarrow c_1 = x, \quad c_2 = y$$

$$\therefore (x, y) = x(1, 0) + y(0, 1)$$

$$\begin{aligned} \Rightarrow T(x, y) &= xT(1, 0) + yT(0, 1) \\ &= x(1, 1) + y(-1, 1) \end{aligned}$$

$$= (x, x) + (-y, y)$$

$$= (x - y, x + y)$$

$$\therefore T(1, 4) = (1 - 4, 1 + 4) = (-3, 5)$$

$$T(-2, 1) = (-2 - 1, -2 + 1)$$

$$= \underline{\underline{(-3, -1)}}$$

4. Let $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be a linear transformation such that $T(1,2) = (1,0)$, $T(-1,1) = (0,1)$. Find $T(x,y)$ and hence evaluate $T(2,0)$.

Ans: Expressing (x,y) as a linear combination of $(1,2)$ and $(-1,1)$ we have

$$\begin{aligned}(x,y) &= c_1(1,2) + c_2(-1,1) \\ &= (c_1, 2c_1) + (-c_2, c_2) \\ &= (c_1 - c_2, 2c_1 + c_2)\end{aligned}$$

$$\Rightarrow c_1 - c_2 = x$$

$$2c_1 + c_2 = y$$

~~Adding these~~

Using Gauss elimination method, augmented

matrix is
$$\begin{bmatrix} 1 & -1 & x \\ 2 & 1 & y \end{bmatrix}$$

$$R_2 \rightarrow R_2 - 2R_1 \sim \begin{bmatrix} 1 & -1 & x \\ 0 & 3 & y - 2x \end{bmatrix}$$

$$R_2 \rightarrow \frac{R_2}{3} \sim \begin{bmatrix} 1 & -1 & x \\ 0 & 1 & \frac{y-2x}{3} \end{bmatrix}$$

$$\Rightarrow c_1 - c_2 = x$$

$$c_2 = \frac{1}{3}(y - 2x)$$

$$\therefore c_1 - \frac{1}{3}(y - 2x) = x$$

$$\Rightarrow c_1 = x + \frac{1}{3}y - \frac{2}{3}x$$

$$= \frac{1}{3}x + \frac{1}{3}y = \frac{1}{3}(x + y)$$

$$\therefore (x, y) = \frac{1}{3}(x+y)(1, 2) + \frac{1}{3}(y-2x)(-1, 1)$$

$$\Rightarrow T(x, y) = \frac{1}{3}(x+y)T(1, 2) + \frac{1}{3}(y-2x)T(-1, 1)$$

$$= \frac{1}{3}(x+y)(1, 0) + \frac{1}{3}(y-2x)(0, 1)$$

$$= \left(\frac{x+y}{3}, 0 \right) + \left(0, \frac{y-2x}{3} \right)$$

$$= \left(\frac{x+y}{3}, \frac{y-2x}{3} \right)$$

$$\therefore T(2, 0) = \left(\frac{2+0}{3}, \frac{0-4}{3} \right) = \underline{\underline{\left(\frac{2}{3}, -\frac{4}{3} \right)}}$$

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5. Find the linear transformation $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ such that $T(1, 0, 0) = (1, 0, -1)$, $T(0, 1, 0) = (2, 1, 1)$, $T(0, 0, 1) = (1, -1, 0)$. Hence find $T(2, -2, 1)$.

Ans: Expressing $(x, y, z) \in \mathbb{R}^3$ as a linear combination of $(1, 0, 0)$, $(0, 1, 0)$ and $(0, 0, 1)$ we have

$$(x, y, z) = c_1(1, 0, 0) + c_2(0, 1, 0) + c_3(0, 0, 1)$$

$$= (c_1, 0, 0) + (0, c_2, 0) + (0, 0, c_3)$$

$$= (c_1, c_2, c_3)$$

$$\therefore C_1 = x, \quad C_2 = y, \quad C_3 = z$$

$$\therefore (x, y, z) = x(1, 0, 0) + y(0, 1, 0) + z(0, 0, 1)$$

$$\Rightarrow T(x, y, z) = xT(1, 0, 0) + yT(0, 1, 0) + zT(0, 0, 1)$$

$$= x(1, 0, -1) + y(2, 1, 1) + z(1, -1, 0)$$

$$= (x, 0, -x) + (2y, y, y) + (z, -z, 0)$$

$$= (x+2y+z, y-z, -x+y)$$

$$T(2, -2, 1) = (2-4+1, -2-1, -2-2)$$

$$= \underline{\underline{(-1, -3, -4)}}$$

6. Let $T: \mathbb{R}^2 \rightarrow \mathbb{R}^3$ be a linear transformation such that $T(1, 2) = (1, 0, 1)$, $T(-1, 1) = (0, 1, -1)$. Find $T(1, 1)$ and $T(0, 0)$.

Ans: Expressing $(x, y) \in \mathbb{R}^2$ as a linear combination of $(1, 2)$ and $(-1, 1)$ we have

$$(x, y) = C_1(1, 2) + C_2(-1, 1)$$

$$= (C_1, 2C_1) + (-C_2, C_2)$$

$$= (C_1 - C_2, 2C_1 + C_2)$$

$$\Rightarrow C_1 - C_2 = x$$

$$2C_1 + C_2 = y$$

By Gauss elimination method, augmented matrix

$$\text{is } \begin{bmatrix} 1 & -1 & x \\ 2 & 1 & y \end{bmatrix}$$

$$R_2 \rightarrow R_2 - 2R_1 \sim \begin{bmatrix} 1 & -1 & x \\ 0 & 3 & y-2x \end{bmatrix}$$

$$R_2 \rightarrow R_2 - R_1 \sim \begin{bmatrix} 1 & -1 & x \\ 0 & 1 & \frac{y-2x}{3} \end{bmatrix}$$

$$\Rightarrow C_1 - C_2 = x$$

$$C_2 = \frac{y-2x}{3}$$

$$\therefore C_1 - \left(\frac{y-2x}{3}\right) = x$$

$$\Rightarrow C_1 = x + \frac{y-2x}{3} = x + \frac{y}{3} - \frac{2x}{3}$$

$$= \frac{y}{3} + \frac{x}{3} = \frac{x+y}{3}$$

$$\therefore (x, y) = \left(\frac{x+y}{3}\right) (1, 2) + \left(\frac{y-2x}{3}\right) (-1, 1)$$

$$= \left(\frac{x+y}{3}, \frac{2(x+y)}{3}\right) + \left(\frac{-(y-2x)}{3}, \frac{y-2x}{3}\right)$$

$$= \underline{x+y, x}$$

$$\therefore T(x, y) = \left(\frac{x+y}{3}\right) T(1, 2) + \left(\frac{y-2x}{3}\right) T(-1, 1)$$

$$= \left(\frac{x+y}{3}\right) (1, 0, 1) + \left(\frac{y-2x}{3}\right) (0, 1, -1)$$

$$= \left(\frac{x+y}{3}, 0, \frac{x+y}{3}\right) + \left(0, \frac{y-2x}{3}, \frac{-(y-2x)}{3}\right)$$

$$= \left(\frac{x+y}{3}, \frac{y-2x}{3}, \frac{x+y-y+2x}{3}\right)$$

$$= \left(\frac{x+y}{3}, \frac{y-2x}{3}, x\right)$$

$$\therefore T(1, 1) = \left(\frac{2}{3}, \frac{-1}{3}, 1\right)$$

$$T(0, 0) = \underline{\underline{(0, 0, 0)}}$$

7. Find the linear transformation $T: \mathbb{R}^2 \rightarrow M_{2,2}$

such that $T(1,0) = \begin{bmatrix} 1 & 2 \\ -1 & 0 \end{bmatrix}$ and $T(2,1) = \begin{bmatrix} -1 & 3 \\ 0 & 2 \end{bmatrix}$.

Hence find $T(1,1)$.

Ans: Expressing $(x,y) \in \mathbb{R}^2$ as a linear combination of $(1,0)$ and $(2,-1)$ we have

$$(x,y) = c_1(1,0) + c_2(2,-1)$$

$$= (c_1, 0) + (2c_2, -c_2)$$

$$= (c_1 + 2c_2, -c_2)$$

$$\Rightarrow c_1 + 2c_2 = x$$

$$-c_2 = y \Rightarrow c_2 = -y$$

$$\therefore c_1 - 2y = x \Rightarrow c_1 = x + 2y$$

$$\therefore (x,y) = (x+2y)(1,0) + (-y)(2,-1)$$

$$\therefore T(x,y) = (x+2y)T(1,0) - yT(2,-1)$$

$$= (x+2y) \begin{bmatrix} 1 & 2 \\ -1 & 0 \end{bmatrix} - y \begin{bmatrix} -1 & 3 \\ 0 & 2 \end{bmatrix}$$

$$= \begin{bmatrix} x+2y & 2x+4y \\ -x-2y & 0 \end{bmatrix} - \begin{bmatrix} -y & 3y \\ 0 & 2y \end{bmatrix}$$

$$= \begin{bmatrix} x+3y & 2x+y \\ -x-2y & -2y \end{bmatrix}$$

$$\therefore T(1,1) = \underline{\underline{\begin{bmatrix} 4 & 3 \\ -3 & -2 \end{bmatrix}}}$$

Linear Transformation given by a matrix

Let A be an $m \times n$ matrix. Then the function $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ defined by $T(V) = AV$ is a linear transformation from \mathbb{R}^n to \mathbb{R}^m .

Problems

1. Define the linear transformation $T: \mathbb{R}^2 \rightarrow \mathbb{R}^3$ by $T(V) = AV$ where $A = \begin{bmatrix} 1 & 2 \\ -2 & 4 \\ -2 & 2 \end{bmatrix}$. Find the dimensions n and m of \mathbb{R}^n and \mathbb{R}^m respectively. Find $T(V)$ where $V \in \mathbb{R}^2$.

Ans: Since A is a 3×2 matrix, $m=3$ and $n=2$.

\therefore Dimension of \mathbb{R}^n is 2 and dimension of \mathbb{R}^m is 3.

Let $V = (x, y) \in \mathbb{R}^2$

$$\therefore T(V) = AV = \begin{bmatrix} 1 & 2 \\ -2 & 4 \\ -2 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} x+2y \\ -2x+4y \\ -2x+2y \end{bmatrix}$$

$\therefore T: \mathbb{R}^2 \rightarrow \mathbb{R}^3$ is defined as

$$\underline{\underline{T(x, y) = (x+2y, -2x+4y, -2x+2y)}}$$

hw
2. Let $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be a linear transformation defined by

$$T(V) = AV \text{ where } A = \begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix}. \text{ Find (a) } T(1, 1)$$

(b) the pre-image of $(1, 2)$, (c) the pre-image of $(0, 0)$.

Ans: $T(V) = AV$, where $V \in \mathbb{R}^2$.

Let $V = (x, y)$

$$\therefore T(v) = Av = \begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -y \\ -x \end{bmatrix}$$

$$\Rightarrow T(x, y) = (-y, -x)$$

$$(a) T(1, 1) = (-1, -1)$$

$$(b) \text{Pre-image of } (1, 2) \text{ is } \{(x, y) \in \mathbb{R}^2 \text{ s.t. } T(x, y) = (1, 2)\}$$

$$\text{i.e.; } (-y, -x) = (1, 2)$$

$$\Rightarrow -y = 1, -x = 2$$

$$\Rightarrow y = -1, x = -2$$

$$\therefore \text{Preimage of } (1, 2) = \underline{\underline{(-2, -1)}}$$

$$(c) \text{Pre-image of } (0, 0) \text{ is } \{(x, y) \in \mathbb{R}^2 \text{ s.t. } T(x, y) = (0, 0)\}$$

$$\text{i.e.; } (-y, -x) = (0, 0)$$

$$\Rightarrow -y = 0, -x = 0$$

$$\Rightarrow y = 0, x = 0$$

$$\therefore \text{Pre image of } (0, 0) = \underline{\underline{(0, 0)}}$$

3 Let $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ be a linear transformation defined

by $T(v) = Av$, where $A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & -1 \end{bmatrix}$. Find (a) $T(1, 1, 1)$

(b) the pre image of $(1, 3)$ (c) the pre-image of $(0, 0)$.

Ans. Given $T(v) = Av$ where $v \in \mathbb{R}^3$. Let $v = (x, y, z)$

$$\therefore T(x, y, z) = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} x+y \\ y-z \end{bmatrix}$$

$$\therefore T(x, y, z) = (x+y, y-z)$$

$$(a) T(1, 1, 1) = (1+1, 1-1) = (2, 0)$$

(b) Let the pre-image of $(1, 3)$ be (x, y, z) .

$$\text{Then } T(x, y, z) = (1, 3)$$

$$\Rightarrow (x+y, y-z) = (1, 3)$$

$$\Rightarrow x+y=1, \quad y-z=3$$

$$\Rightarrow x=1-y, \quad z=y-3$$

Let $y=k$, then $x=1-k$ and $z=k-3$

$$\therefore \text{The pre image of } (1, 3) = \underline{\underline{\{(1-k, k, k-3) / k \in \mathbb{R}\}}}$$

(c) The pre image of $(0, 0)$ be (x, y, z) .

$$\text{Then } T(x, y, z) = (0, 0)$$

$$\Rightarrow (x+y, y-z) = (0, 0)$$

$$\Rightarrow x+y=0, \quad y-z=0$$

$$\Rightarrow x=-y, \quad z=y$$

Let $y=k$, then $x=-k, z=k$

$$\text{ie, The preimage of } (0, 0) = \{(-k, k, k) / k \in \mathbb{R}\}$$

4. For the linear transformation $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ given

by the matrix $A = \begin{bmatrix} a & -b \\ b & a \end{bmatrix}$, find a and b

Such that $T(12, 5) = (13, 0)$.

Ans: Given $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ and $A = \begin{bmatrix} a & -b \\ b & a \end{bmatrix}$

$$\begin{aligned} \text{For } (x, y) \in \mathbb{R}^2, \quad T(x, y) &= \begin{bmatrix} a & -b \\ b & a \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} \\ &= \begin{bmatrix} ax - by \\ bx + ay \end{bmatrix} \end{aligned}$$

$$T(12, 5) = (13, 0) \Rightarrow \begin{bmatrix} a \cdot 12 - b \cdot 5 \\ b \cdot 12 + a \cdot 5 \end{bmatrix} = \begin{bmatrix} 13 \\ 0 \end{bmatrix}$$

$$\Rightarrow 12a - 5b = 13$$

$$12b + 5a = 0$$

$$\Rightarrow 12a - 5b = 13$$

$$5a + 12b = 0$$

$$\text{Augmented matrix} = \begin{bmatrix} 12 & -5 & 13 \\ 5 & 12 & 0 \end{bmatrix} R_1 \rightarrow \frac{R_1}{12}$$

$$\sim \begin{bmatrix} 1 & -5/12 & 13/12 \\ 5 & 12 & 0 \end{bmatrix} R_2 \rightarrow R_2 - 5R_1$$

$$\sim \begin{bmatrix} 1 & -5/12 & 13/12 \\ 0 & 169/12 & -65/12 \end{bmatrix} R_2 \rightarrow R_2 \cdot \frac{12}{169}$$

$$\sim \begin{bmatrix} 1 & -5/12 & 13/12 \\ 0 & 1 & -65/169 \end{bmatrix}$$

$$\Rightarrow a - \frac{5}{12}b = \frac{13}{12}$$

$$b = \frac{-65}{169} = \frac{-5}{13}$$

$$\therefore a = \frac{13}{12} + \frac{5}{12}b = \frac{13}{12} - \frac{25}{12 \times 13}$$

$$= \frac{12}{13}$$

$$\therefore \underline{a = \frac{12}{13} \text{ and } b = \frac{-5}{13}}$$

HW 5. For the linear transformation $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ given by the matrix $A = \begin{bmatrix} a & 2 \\ 3 & a+b \end{bmatrix}$, find a and b such that $T(1,2) = (5,7)$.

Ans: Given $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ and $A = \begin{bmatrix} a & 2 \\ 3 & a+b \end{bmatrix}$

$$\therefore \text{For } (x,y) \in \mathbb{R}^2, T(x,y) = \begin{bmatrix} a & 2 \\ 3 & a+b \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$= \begin{bmatrix} ax + 2y \\ 3x + (a+b)y \end{bmatrix}$$

$$T(1,2) = (5,7) \Rightarrow \begin{bmatrix} a \cdot 1 + 2 \cdot a \\ 3 \cdot 1 + (a+b) \cdot 2 \end{bmatrix} = \begin{bmatrix} 5 \\ 7 \end{bmatrix}$$

$$\Rightarrow a + 4 = 5$$

$$3 + (a+b) \cdot 2 = 7$$

$$a + 4 = 5 \Rightarrow a = 5 - 4 = 1$$

$$\therefore 3 + (1+b) \cdot 2 = 7 \Rightarrow 3 + 2 + 2b = 7$$

$$\Rightarrow 5 + 2b = 7$$

$$\Rightarrow 2b = 7 - 5 = 2$$

$$\Rightarrow b = \frac{2}{2} = 1$$

$$\therefore \underline{\underline{a=1, b=1}}$$

Rotation in \mathbb{R}^2

Standard rotation matrix for a counter clockwise rotation by angle θ is

$$R(\theta) = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

1. Find the linear transformation which rotates every vector in \mathbb{R}^2 counter clockwise about the origin through the angle θ . Also find LT when $\theta = 45^\circ$

Ans: Linear transformation $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is defined as,

for $(x, y) \in \mathbb{R}^2$

$$\begin{aligned} T(x, y) &= R(\theta) \cdot \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} \\ &= \begin{bmatrix} x \cos \theta - y \sin \theta \\ x \sin \theta + y \cos \theta \end{bmatrix} \end{aligned}$$

$$\therefore T(x, y) = (x \cos \theta - y \sin \theta, x \sin \theta + y \cos \theta)$$

When $\theta = 45^\circ$

$$T(x, y) = (x \cos 45^\circ - y \sin 45^\circ, x \sin 45^\circ + y \cos 45^\circ)$$

$$= \left(\frac{x}{\sqrt{2}} - \frac{y}{\sqrt{2}}, \frac{x}{\sqrt{2}} + \frac{y}{\sqrt{2}} \right)$$

Projection in \mathbb{R}^3

The linear transformation $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ represented by the matrix $A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$ is defined by

$$T(v) = Av$$

$$\text{i.e. } T(x, y, z) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} x \\ y \\ 0 \end{bmatrix}$$

$$\therefore T(x, y, z) = (x, y, 0)$$

We can consider the point $(x, y, 0)$ in \mathbb{R}^3 as the point (x, y) in the xy -plane. i.e.; T orthogonally project every vector in \mathbb{R}^3 to xy -plane \mathbb{R}^2 .

Similarly if $A = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$, then the projection is to

the yz -plane and if $A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$, then the projection is to the xz -plane.

Kernel and Nullity

Kernel of a linear transformation $T: V \rightarrow W$ is the set of all vectors $v \in V$ that are mapped by T into the zero vector in W and is denoted as $\ker(T)$.

$$\ker(T) = \{v \in V : T(v) = 0\}$$

Note

- 1) kernel of a linear transformation is always non-empty, since if T is a linear transformation $T(0) = 0$. \therefore The zero vector belongs to the kernel.
- 2) kernel of LT $T: V \rightarrow W$ is a subspace of V .

Nullity

Let $T: V \rightarrow W$ be a linear transformation. The dimension of kernel of T is called nullity of T . If $\ker(T)$ only zero vector, then nullity of $T = 0$.

Problems

1. Find the kernel of the linear transformation

$$T: \mathbb{R}^2 \rightarrow \mathbb{R}^3 \text{ defined by } T(x_1, x_2) = (x_1 - 2x_2, 3x_1, -5x_1)$$

Ans: To find $\ker(T)$ we need to find all $v = (x_1, x_2)$ in \mathbb{R}^2 such that $T(x_1, x_2) = 0$

$$\Rightarrow (x_1 - 2x_2, 3x_1, -5x_1) = (0, 0, 0)$$

$$\Rightarrow x_1 - 2x_2 = 0$$

$$3x_1 = 0$$

$$-5x_1 = 0$$

$$\therefore x_1 = 0. \quad x_1 - 2x_2 = 0$$

$$\Rightarrow 0 - 2x_2 = 0 \Rightarrow x_2 = 0$$

$$\therefore \ker(T) = \{(0, 0)\} = \{0\}$$

2. Find the kernel and nullity of the linear transformation

$$T: \mathbb{R}^3 \rightarrow \mathbb{R}^2 \text{ defined by } T(x) = Ax \text{ where } A = \begin{bmatrix} 3 & -3 & -6 \\ -1 & 2 & 3 \end{bmatrix}.$$

Ans: To find $\ker(T)$, we need to find all $x = (x_1, x_2, x_3)$

$$\text{in } \mathbb{R}^3 \text{ such that } T(x_1, x_2, x_3) = 0$$

$$\Rightarrow \begin{bmatrix} 3 & -3 & -6 \\ -1 & 2 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 3x_1 - 3x_2 - 6x_3 \\ -x_1 + 2x_2 + 3x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow \begin{aligned} 3x_1 - 3x_2 - 6x_3 &= 0 \\ -x_1 + 2x_2 + 3x_3 &= 0 \end{aligned}$$

By Gauss elimination method, augmented matrix

$$= \begin{bmatrix} 3 & -3 & -6 & 0 \\ -1 & 2 & 3 & 0 \end{bmatrix} R_1 \rightarrow \frac{R_1}{3}$$

$$\sim \begin{bmatrix} 1 & -1 & -2 & 0 \\ -1 & 2 & 3 & 0 \end{bmatrix} R_2 \rightarrow R_2 + R_1$$

$$\sim \begin{bmatrix} 1 & -1 & -2 & 0 \\ 0 & 1 & 1 & 0 \end{bmatrix}$$

$$\therefore x_1 - x_2 - 2x_3 = 0$$

$$x_2 + x_3 = 0$$

$$\text{Put } x_2 = t \quad \therefore x_2 + x_3 = 0 \\ \Rightarrow x_3 = -x_2 = -t$$

$$\text{Also } x_1 - x_2 - 2x_3 = 0 \Rightarrow x_1 - t + 2t = 0 \\ \Rightarrow x_1 + t = 0 \Rightarrow x_1 = -t$$

$$\therefore \ker T = \{ (-t, t, -t) : t \in \mathbb{R} \}$$

$$= \{ t(-1, 1, -1) : t \in \mathbb{R} \} = \text{span} \{ (-1, 1, -1) \}$$

So kernel of T is a subspace of \mathbb{R}^3 spanned by a vector $(1, -1, 1)$.

\therefore Dimension of kernel of $T = 1$

\therefore Nullity of $T = 1$

3 Find the kernel and nullity of the linear transformation $T: \mathbb{R}^5 \rightarrow \mathbb{R}^4$ defined by $T(x) = Ax$ where $x \in \mathbb{R}^5$ and

$$A = \begin{bmatrix} 2 & 1 & 3 & 1 & 0 \\ 1 & 2 & 0 & 1 & -1 \\ -3 & 0 & -6 & 0 & 3 \\ 0 & 0 & 0 & 2 & 8 \end{bmatrix}$$

Ans: To find $\ker(T)$, we need to find $x = (x_1, x_2, x_3, x_4, x_5)$

in \mathbb{R}^5 such that $T(x_1, x_2, x_3, x_4, x_5) = 0$

$$\Rightarrow \begin{bmatrix} 2 & 1 & 3 & 1 & 0 \\ 1 & 2 & 0 & 1 & -1 \\ -3 & 0 & -6 & 0 & 3 \\ 0 & 0 & 0 & 2 & 8 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 2x_1 + x_2 + 3x_3 + x_4 \\ x_1 + 2x_2 + x_4 - x_5 \\ -3x_1 - 6x_3 + 3x_5 \\ 2x_4 + 8x_5 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow 2x_1 + x_2 + 3x_3 + x_4 = 0$$

$$x_1 + 2x_2 + x_4 - x_5 = 0$$

$$-3x_1 - 6x_3 + 3x_5 = 0$$

$$2x_4 + 8x_5 = 0$$

Using Gauss elimination method, augmented matrix is

$$\begin{bmatrix} 2 & 1 & 3 & 1 & 0 & 0 \\ 1 & 2 & 0 & 1 & -1 & 0 \\ -3 & 0 & -6 & 0 & 3 & 0 \\ 0 & 0 & 0 & 2 & 8 & 0 \end{bmatrix} R_1 \rightarrow \frac{R_1}{2}$$

$$\sim \begin{bmatrix} 1 & 1/2 & 3/2 & 1/2 & 0 & 0 \\ 1 & 2 & 0 & 1 & -1 & 0 \\ -3 & 0 & -6 & 0 & 3 & 0 \\ 0 & 0 & 0 & 2 & 8 & 0 \end{bmatrix} \begin{array}{l} R_2 \rightarrow R_2 - R_1 \\ R_3 \rightarrow R_3 + 3R_1 \end{array}$$

$$\sim \begin{bmatrix} 1 & 1/2 & 3/2 & 1/2 & 0 & 0 \\ 0 & 3/2 & -3/2 & 1/2 & -1 & 0 \\ 0 & 3/2 & -3/2 & 3/2 & 3 & 0 \\ 0 & 0 & 0 & 2 & 8 & 0 \end{bmatrix} R_2 \rightarrow R_2 \times \frac{2}{3}$$

$$\sim \begin{bmatrix} 1 & 1/2 & 3/2 & 1/2 & 0 & 0 \\ 0 & 1 & -1 & 1/3 & -2/3 & 0 \\ 0 & 3/2 & -3/2 & 3/2 & 3 & 0 \\ 0 & 0 & 0 & 2 & 8 & 0 \end{bmatrix} R_3 \rightarrow R_3 - \frac{3}{2}R_2$$

$$\sim \begin{bmatrix} 1 & 1/2 & 3/2 & 1/2 & 0 & 0 \\ 0 & 1 & -1 & 1/3 & -2/3 & 0 \\ 0 & 0 & 0 & 1 & 4 & 0 \\ 0 & 0 & 0 & 2 & 8 & 0 \end{bmatrix} R_4 \rightarrow R_4 - 2R_3$$

$$\sim \begin{bmatrix} 1 & 1/2 & 3/2 & 1/2 & 0 & 0 \\ 0 & 1 & -1 & 1/3 & -2/3 & 0 \\ 0 & 0 & 0 & 1 & 4 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

\therefore Rank = 3 < no. of unknowns = 5. So we have to assign arbitrary values to $5 - 3 = 2$ variables.

$$x_1 + \frac{1}{2}x_2 + \frac{3}{2}x_3 + \frac{1}{2}x_4 = 0$$

$$x_2 - x_3 + \frac{1}{3}x_4 - \frac{2}{3}x_5 = 0$$

$$x_4 + 4x_5 = 0$$

Let $x_3 = s$ and $x_5 = t$

$$\therefore x_4 + 4x_5 = 0 \Rightarrow x_4 = -4x_5 = -4t$$

$$x_2 - x_3 + \frac{1}{3}x_4 - \frac{2}{3}x_5 = 0$$

$$\Rightarrow x_2 - s + \frac{1}{3}x - 4t - \frac{2}{3}xt = 0$$

$$\Rightarrow x_2 - s - \frac{4t}{3} - \frac{2t}{3} = 0$$

$$\Rightarrow x_2 - s - \frac{6t}{3} = 0$$

$$\Rightarrow x_2 = s + 2t$$

$$x_1 + \frac{1}{2}x_2 + \frac{3}{2}x_3 + \frac{1}{2}x_4 = 0$$

$$\Rightarrow x_1 + \frac{1}{2}(s+2t) + \frac{3}{2}(s) + \frac{1}{2}(-4t) = 0$$

$$\Rightarrow x_1 + \frac{1}{2}s + t + \frac{3}{2}s - 2t = 0$$

$$\Rightarrow x_1 + 2s - t = 0$$

$$\Rightarrow x_1 = -2s + t$$

$$\therefore \ker T = \left\{ (-2s+t, s+2t, s, -4t, t) \mid s, t \in \mathbb{R} \right\}$$

$$\text{ie; } x = \begin{bmatrix} -2s+t \\ s+2t \\ s \\ -4t \\ t \end{bmatrix} = s \begin{bmatrix} -2 \\ 1 \\ 1 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} 1 \\ 2 \\ 0 \\ -4 \\ 1 \end{bmatrix}$$

$\therefore B = \left\{ (-2, 1, 1, 0, 0), (1, 2, 0, -4, 1) \right\}$ is a basis for the kernel of T

$$\therefore \text{Nullity of } T = \underline{\underline{2}}$$

4. Find a basis for the kernel and nullity of the linear transformation $T: \mathbb{R}^4 \rightarrow \mathbb{R}^4$ defined by $T(x) = Ax$,

$$\text{where } x \in \mathbb{R}^4 \text{ and } A = \begin{bmatrix} 2 & -1 & 0 & 1 \\ 3 & 2 & 1 & -1 \\ 0 & 1 & -1 & 2 \\ 5 & 0 & -2 & 2 \end{bmatrix}$$

Ans: To find $\ker(T)$, we need to find $(x_1, x_2, x_3, x_4) \in \mathbb{R}^4$

Such that $T(x_1, x_2, x_3, x_4) = 0$

$$\Rightarrow \begin{bmatrix} 2 & -1 & 0 & 1 \\ 3 & 2 & 1 & -1 \\ 0 & 1 & -1 & 2 \\ 5 & 0 & -2 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow 2x_1 - x_2 + x_4 = 0$$

$$3x_1 + 2x_2 + x_3 - x_4 = 0$$

$$x_2 - x_3 + 2x_4 = 0$$

$$5x_1 - 2x_3 + 2x_4 = 0$$

Using Gauss elimination method, augmented matrix

$$= \begin{bmatrix} 2 & -1 & 0 & 1 & 0 \\ 3 & 2 & 1 & -1 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 5 & 0 & -2 & 2 & 0 \end{bmatrix} R_1 \rightarrow \frac{R_1}{2}$$

$$\sim \begin{bmatrix} 1 & -\frac{1}{2} & 0 & \frac{1}{2} & 0 \\ 3 & 2 & 1 & -1 & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 5 & 0 & -2 & 2 & 0 \end{bmatrix} \begin{array}{l} R_2 \rightarrow R_2 - 3R_1 \\ R_4 \rightarrow R_4 - 5R_1 \end{array}$$

$$\sim \begin{bmatrix} 1 & -\frac{1}{2} & 0 & \frac{1}{2} & 0 \\ 0 & \frac{7}{2} & 1 & -\frac{5}{2} & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & \frac{5}{2} & -2 & -\frac{1}{2} & 0 \end{bmatrix} R_2 \rightarrow R_2 \times \frac{2}{7}$$

$$\sim \begin{bmatrix} 1 & -\frac{1}{2} & 0 & \frac{1}{2} & 0 \\ 0 & 1 & \frac{2}{7} & -\frac{5}{7} & 0 \\ 0 & 1 & -1 & 2 & 0 \\ 0 & \frac{5}{2} & -2 & -\frac{1}{2} & 0 \end{bmatrix} \begin{array}{l} R_3 \rightarrow R_3 - R_2 \\ R_4 \rightarrow R_4 - \frac{5}{2}R_2 \end{array}$$

$$\sim \begin{bmatrix} 1 & -\frac{1}{2} & 0 & \frac{1}{2} & 0 \\ 0 & 1 & \frac{2}{7} & -\frac{5}{7} & 0 \\ 0 & 0 & -\frac{9}{7} & \frac{19}{7} & 0 \\ 0 & 0 & -\frac{19}{7} & \frac{9}{7} & 0 \end{bmatrix} R_3 \rightarrow R_3 \times \frac{-7}{9}$$

$$\sim \begin{bmatrix} 1 & -\frac{1}{2} & 0 & \frac{1}{2} & 0 \\ 0 & 1 & \frac{2}{7} & -\frac{5}{7} & 0 \\ 0 & 0 & 1 & -\frac{19}{9} & 0 \\ 0 & 0 & -\frac{19}{7} & \frac{9}{7} & 0 \end{bmatrix} \quad R_4 \rightarrow R_4 + \frac{19}{7} R_3$$

$$\sim \begin{bmatrix} 1 & -\frac{1}{2} & 0 & \frac{1}{2} & 0 \\ 0 & 1 & \frac{2}{7} & -\frac{5}{7} & 0 \\ 0 & 0 & 1 & -\frac{19}{9} & 0 \\ 0 & 0 & 0 & -\frac{35}{19} & 0 \end{bmatrix} \quad R_4 \rightarrow R_4 \times \frac{-19}{35}$$

$$\sim \begin{bmatrix} 1 & -\frac{1}{2} & 0 & \frac{1}{2} & 0 \\ 0 & 1 & \frac{2}{7} & -\frac{5}{7} & 0 \\ 0 & 0 & 1 & -\frac{19}{9} & 0 \\ 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$

\therefore Rank = no. of unknowns.

$$x_1 - \frac{1}{2}x_2 + \frac{1}{2}x_4 = 0$$

$$x_2 + \frac{2}{7}x_3 - \frac{5}{7}x_4 = 0$$

$$x_3 - \frac{19}{9}x_4 = 0$$

$$x_4 = 0$$

$$x_3 - \frac{19}{9}x_4 = 0 \Rightarrow x_3 - 0 = 0 \Rightarrow x_3 = 0$$

$$x_2 + \frac{2}{7}x_3 - \frac{5}{7}x_4 = 0 \Rightarrow x_2 + 0 - 0 = 0 \Rightarrow x_2 = 0$$

$$x_1 - \frac{1}{2}x_2 + \frac{1}{2}x_4 = 0 \Rightarrow x_1 - 0 + 0 = 0 \Rightarrow x_1 = 0$$

$$\therefore \ker T = \left\{ (0, 0, 0, 0) \right\}$$

So Nullity of T = 0

Range of a linear transformation.

The range of a linear transformation $T: V \rightarrow W$ is the set of vectors in W which are images of elements of V . i.e.; $\text{range}(T) = \{T(v) : v \in V\}$

Rank of a linear transformation.

Let $T: V \rightarrow W$ be a linear transformation. The dimension of range of T is called rank of T , denoted by $r(T)$.

Note

1. The range of a linear transformation $T: V \rightarrow W$ is a subspace of W .
2. If $T: V \rightarrow W$ is a linear transformation defined by $T(v) = Av$, then the range of T is equal to the subspace spanned by the column vectors of A . (i.e.; the column space of A).
3. Let A be an $m \times n$ matrix. Then the columns of A corresponding to the columns of leading variables of its row echelon form constitute a basis for the column space of A .

Steps to find the basis for the range of a LT

- 1) Write the given linear transformation in the form $T(v) = Av$
2. Reduce the matrix A to its row echelon form R .
3. Note the columns of R corresponding to the

leading variables.

4. Form the basis for the range of T using the corresponding columns of A .

Sum of Rank and Nullity (Rank Nullity Theorem)

Let $T: V \rightarrow W$ be a linear transformation from an n -dimensional vector space V into a vector space W . Then the sum of the dimensions of the range of T and kernel of T is equal to the dimension of the domain V .

i.e.; $\text{Rank}(T) + \text{Nullity}(T) = n$.

Problems

1. Find the range and rank of the linear transformation $T: \mathbb{R}^5 \rightarrow \mathbb{R}^4$ defined by $T(x) = Ax$, where $x \in \mathbb{R}^5$ and

$$A = \begin{bmatrix} 2 & 1 & 3 & 1 & 0 \\ 1 & 2 & 0 & 1 & -1 \\ -3 & 0 & -6 & 0 & 3 \\ 0 & 0 & 0 & 2 & 8 \end{bmatrix}$$

Ans: Given $T(x) = Ax$ where

$$A = \begin{bmatrix} 2 & 1 & 3 & 1 & 0 \\ 1 & 2 & 0 & 1 & -1 \\ -3 & 0 & -6 & 0 & 3 \\ 0 & 0 & 0 & 2 & 8 \end{bmatrix}$$

Now we have to reduce A to its echelon form.

$$A = \begin{bmatrix} 2 & 1 & 3 & 1 & 0 \\ 1 & 2 & 0 & 1 & -1 \\ -3 & 0 & -6 & 0 & 3 \\ 0 & 0 & 0 & 2 & 8 \end{bmatrix} \quad R_1 \rightarrow \frac{R_1}{2}$$

$$\sim \begin{bmatrix} 1 & \frac{1}{2} & \frac{3}{2} & \frac{1}{2} & 0 \\ 1 & 2 & 0 & 1 & -1 \\ -3 & 0 & -6 & 0 & 3 \\ 0 & 0 & 0 & 2 & 8 \end{bmatrix} \begin{array}{l} R_2 \rightarrow R_2 - R_1 \\ R_3 \rightarrow R_3 + 3R_1 \end{array}$$

$$\sim \begin{bmatrix} 1 & \frac{1}{2} & \frac{3}{2} & \frac{1}{2} & 0 \\ 0 & \frac{3}{2} & -\frac{3}{2} & \frac{1}{2} & -1 \\ 0 & \frac{3}{2} & -\frac{3}{2} & \frac{3}{2} & 3 \\ 0 & 0 & 0 & 2 & 8 \end{bmatrix} R_2 \rightarrow R_2 \times \frac{2}{3}$$

$$\sim \begin{bmatrix} 1 & \frac{1}{2} & \frac{3}{2} & \frac{1}{2} & 0 \\ 0 & 1 & -1 & \frac{1}{3} & -\frac{2}{3} \\ 0 & \frac{3}{2} & -\frac{3}{2} & \frac{3}{2} & 3 \\ 0 & 0 & 0 & 2 & 8 \end{bmatrix} R_3 \rightarrow R_3 - \frac{3}{2}R_2$$

$$\sim \begin{bmatrix} 1 & \frac{1}{2} & \frac{3}{2} & \frac{1}{2} & 0 \\ 0 & 1 & -1 & \frac{1}{3} & -\frac{2}{3} \\ 0 & 0 & 0 & 1 & 4 \\ 0 & 0 & 0 & 2 & 8 \end{bmatrix} R_4 \rightarrow R_4 - 2R_3$$

$$\sim \begin{bmatrix} 1 & \frac{1}{2} & \frac{3}{2} & \frac{1}{2} & 0 \\ 0 & 1 & -1 & \frac{1}{3} & -\frac{2}{3} \\ 0 & 0 & 0 & 1 & 4 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Here the leading variables in the row echelon form corresponds to the first, second and fourth columns of A.

$$\therefore \text{Basis of range of } T = \left\{ (2, 1, -3, 0), (1, 2, 0, 0), (1, 1, 0, 2) \right\}$$

$$\therefore \text{Rank of } T = \underline{\underline{3}}$$

Hw 2. Find a basis for the range and rank of the linear transformation $T: \mathbb{R}^4 \rightarrow \mathbb{R}^3$ defined by $T(X) = AX$, where

$$X \in \mathbb{R}^4 \text{ and } A = \begin{bmatrix} 1 & -1 & 0 & 3 \\ 1 & 1 & -3 & -1 \\ -2 & 0 & 3 & -2 \end{bmatrix}$$

Ans: Reducing A to its echelon form,

$$A = \begin{bmatrix} 1 & -1 & 0 & 3 \\ 1 & 1 & -3 & -1 \\ -2 & 0 & 3 & -2 \end{bmatrix} \begin{array}{l} R_2 \rightarrow R_2 - R_1 \\ R_3 \rightarrow R_3 + 2R_1 \end{array}$$

$$\sim \begin{bmatrix} 1 & -1 & 0 & 3 \\ 0 & 2 & -3 & -4 \\ 0 & -2 & 3 & 4 \end{bmatrix} \begin{array}{l} R_2 \rightarrow \frac{R_2}{2} \\ R_3 \rightarrow R_3 + 2R_2 \end{array}$$

$$\sim \begin{bmatrix} 1 & -1 & 0 & 3 \\ 0 & 1 & -3/2 & -2 \\ 0 & -2 & 3 & 4 \end{bmatrix} \begin{array}{l} R_3 \rightarrow R_3 + 2R_2 \end{array}$$

$$\sim \begin{bmatrix} 1 & -1 & 0 & 3 \\ 0 & 1 & -3/2 & -2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Here the leading variables in the row echelon form corresponds to the first and second columns of A .

$$\therefore \text{Basis for range of } T = \left\{ (1, 1, -2), (-1, 1, 0) \right\}$$

$$\therefore \text{Rank of } T = \underline{\underline{2}}$$

3. Let $T: \mathbb{R}^5 \rightarrow \mathbb{R}^8$ be a linear transformation.

(a) Find the dimension of the kernel of T when the dimension of the range is 3.

(b) Find the rank of T when the nullity of T is 2

(c) Find the rank of T when $\ker(T) = \{0\}$.

Ans: Since $T: \mathbb{R}^5 \rightarrow \mathbb{R}^8$, dimension of domain = 5
i.e.; $n=5$.

$$\text{We have Rank}(T) + \text{Nullity}(T) = 5 \quad \text{--- ①}$$

a) Given dimension of the range = 3

$$\text{i.e.; Rank}(T) = 3$$

$$\therefore \text{①} \Rightarrow 3 + \text{Nullity}(T) = 5$$

$$\Rightarrow \text{Nullity}(T) = 5 - 3 = 2.$$

$$\text{i.e.; dimension of } \ker(T) = \underline{\underline{2}}$$

b) Given Nullity $(T) = 2$

$$\therefore \text{①} \Rightarrow \text{Rank}(T) + 2 = 5$$

$$\Rightarrow \text{Rank}(T) = 5 - 2 = \underline{\underline{3}}$$

(c) $\ker(T) = \{0\} \Rightarrow$ dimension of $\ker(T) = 0$

$$\text{i.e.; Nullity}(T) = 0$$

$$\therefore \text{①} \Rightarrow \text{Rank}(T) + 0 = 5$$

$$\Rightarrow \text{Rank}(T) = \underline{\underline{5}}$$

4. The linear transformation $T: \mathbb{R}^2 \rightarrow \mathbb{R}^3$ by $T(x) = Ax$

where $A = \begin{bmatrix} 5 & -3 \\ 1 & 1 \\ 1 & -1 \end{bmatrix}$. Find (a) $\ker T$ (b) Nullity (T)

(c) range (T) (d) rank (T). Also verify that $\text{rank}(T) + \text{nullity}(T) = \dim(\mathbb{R}^2)$.

Ans: a) To find $\ker(T)$, we need to find $(x_1, x_2) \in \mathbb{R}^2$

Such that $T(x_1, x_2) = 0$

$$\Rightarrow \begin{bmatrix} 5 & -3 \\ 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 5x_1 - 3x_2 \\ x_1 + x_2 \\ x_1 - x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow 5x_1 - 3x_2 = 0$$

$$x_1 + x_2 = 0$$

$$x_1 - x_2 = 0$$

Augmented matrix = $\begin{bmatrix} 5 & -3 & 0 \\ 1 & 1 & 0 \\ 1 & -1 & 0 \end{bmatrix} R_1 \rightarrow \frac{R_1}{5}$

$$\sim \begin{bmatrix} 1 & -3/5 & 0 \\ 1 & 1 & 0 \\ 1 & -1 & 0 \end{bmatrix} \begin{array}{l} R_2 \rightarrow R_2 - R_1 \\ R_3 \rightarrow R_3 - R_1 \end{array}$$

$$\sim \begin{bmatrix} 1 & -3/5 & 0 \\ 0 & 8/5 & 0 \\ 0 & -2/5 & 0 \end{bmatrix} R_2 \rightarrow R_2 \times \frac{5}{8}$$

$$\sim \begin{bmatrix} 1 & -3/5 & 0 \\ 0 & 1 & 0 \\ 0 & -2/5 & 0 \end{bmatrix} R_3 \rightarrow R_3 + \frac{2}{5} R_2$$

$$\sim \begin{bmatrix} 1 & -3/5 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\Rightarrow x_1 - \frac{3}{5}x_2 = 0$$

$$x_2 = 0$$

$$\therefore x_1 - 0 = 0 \Rightarrow x_1 = 0$$

$$\therefore \ker(T) = \{(0, 0)\}$$

$$(b) \text{ nullity } (T) = 0$$

$$(c) \text{ From part (a) } \begin{bmatrix} 5 & -3 \\ 1 & 1 \\ 1 & -1 \end{bmatrix} \sim \begin{bmatrix} 1 & -3/5 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$$

\therefore leading variables in row echelon form corresponds to the first and second columns of A

$$\therefore \text{Basis for range } (T) = \{(5, 1, 1), (-3, 1, -1)\}$$

$$(d) \text{ Rank } (T) = 2$$

$$\text{Now rank } (T) + \text{nullity } (T) = 2 + 0 = 2 = \dim(\mathbb{R}^2).$$

Standard Matrix of a linear Transformation

Let $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear transformation and $B = \{e_1, e_2, \dots, e_n\}$ be the standard basis for \mathbb{R}^n . Then standard matrix for a linear transformation is

defined by $A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \dots & \dots & \dots & \dots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}_{m \times n}$ where

$$T(e_i) = \begin{bmatrix} a_{1i} \\ a_{2i} \\ \vdots \\ a_{mi} \end{bmatrix} \text{ for } i=1, 2, \dots, n.$$

$$T(v) = Av \text{ for all } v \in \mathbb{R}^n.$$

Problems

1. Find the standard matrix for the linear transformation

$$T: \mathbb{R}^3 \rightarrow \mathbb{R}^2 \text{ defined by } T(x, y, z) = (x - 2y, 3x + y - z).$$

Ans: ~~Let~~ The standard basis of \mathbb{R}^3 is $\{(1, 0, 0), (0, 1, 0), (0, 0, 1)\}$

$$\therefore e_1 = (1, 0, 0), e_2 = (0, 1, 0), e_3 = (0, 0, 1)$$

$$T(e_1) = T(1, 0, 0) = (1 - 0, 3 + 0 - 0) = (1, 3)$$

$$T(e_2) = T(0, 1, 0) = (-2, 1)$$

$$T(e_3) = T(0, 0, 1) = (0, -1)$$

$$\therefore \text{standard matrix } A = [T(e_1) \quad T(e_2) \quad T(e_3)]$$

$$= \begin{bmatrix} 1 & -2 & 0 \\ 3 & 1 & -1 \end{bmatrix}$$

2. Let $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be a linear transformation defined by $T(x, y) = (x - y, x + 3y)$. Find the standard matrix for T .

Ans: The standard basis of \mathbb{R}^2 is $\{(1, 0), (0, 1)\}$

$$\therefore e_1 = (1, 0), \quad e_2 = (0, 1)$$

$$T(e_1) = T(1, 0) = (1, 1)$$

$$T(e_2) = T(0, 1) = (-1, 3)$$

$$\therefore \text{standard matrix } A = [T(e_1) \quad T(e_2)]$$

$$= \begin{bmatrix} 1 & -1 \\ 1 & 3 \end{bmatrix}$$

3. Let $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be a linear transformation defined by $T(x, y) = (x + y, 2x - y)$. Find the standard matrix for T .

Ans: The standard basis of \mathbb{R}^2 is $\{(1, 0), (0, 1)\}$

$$\therefore e_1 = (1, 0), \quad e_2 = (0, 1)$$

$$T(e_1) = T(1, 0) = (1, 2)$$

$$T(e_2) = T(0, 1) = (1, -1)$$

$$\therefore \text{standard matrix } A = [T(e_1) \quad T(e_2)]$$

$$= \begin{bmatrix} 1 & 1 \\ 2 & -1 \end{bmatrix}$$

4. Use the standard matrix for the linear transformation

$T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ defined by $T(x, y, z) = (2x + y, 3y - z)$ to find

the image of the vector $v = (0, 1, -1)$.

Ans: The standard basis of \mathbb{R}^3 is $\{(1, 0, 0), (0, 1, 0), (0, 0, 1)\}$

$$\therefore e_1 = (1, 0, 0), e_2 = (0, 1, 0), e_3 = (0, 0, 1)$$

$$\therefore T(e_1) = T(1, 0, 0) = (2, 0)$$

$$T(e_2) = T(0, 1, 0) = (1, 3)$$

$$T(e_3) = T(0, 0, 1) = (0, -1)$$

$$\therefore \text{Standard matrix } A = \begin{bmatrix} 2 & 1 & 0 \\ 0 & 3 & -1 \end{bmatrix}$$

Now $T(v) = Av$.

$$\therefore T(0, 1, -1) = \begin{bmatrix} 2 & 1 & 0 \\ 0 & 3 & -1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 1 \\ 4 \end{bmatrix}$$

$$\therefore T(0, 1, -1) = \underline{\underline{(1, 4)}}$$

5. Find $T(1, -5, 2)$ by using the standard matrix for the linear transformation $T: \mathbb{R}^3 \rightarrow \mathbb{R}^4$ defined by

$$T(x, y, z) = (2x, x+y, y+z, x+z)$$

Ans: Standard basis of \mathbb{R}^3 is $\{(1, 0, 0), (0, 1, 0), (0, 0, 1)\}$

$$\therefore e_1 = (1, 0, 0), e_2 = (0, 1, 0), e_3 = (0, 0, 1)$$

$$\therefore T(e_1) = T(1, 0, 0) = (2, 1, 0, 1)$$

$$T(e_2) = T(0, 1, 0) = (0, 1, 1, 0)$$

$$T(e_3) = T(0, 0, 1) = (0, 0, 1, 1)$$

$$\therefore \text{Standard matrix } A = \begin{bmatrix} 2 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix}$$

Now $T(v) = Av$

$$\therefore T(1, -5, 2) = \begin{bmatrix} 2 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ -5 \\ 2 \end{bmatrix} = \begin{bmatrix} 2 \\ -4 \\ 3 \\ 3 \end{bmatrix}$$

$$\therefore T(1, -5, 2) = \underline{\underline{(2, -4, -3, 3)}}$$

Matrix of a linear transformation

Let T be a linear transformation from an n -dimensional vector space V into an m -dimensional vector space W , and let $B = \{v_1, v_2, \dots, v_n\}$ be a basis for V and $C = \{w_1, w_2, \dots, w_m\}$ be a basis for W . Then the matrix of T with respect to B and C is defined by

$$\left[T \right]_{B,C} = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix} \text{ where } \left[T(v_i) \right]_C = \begin{bmatrix} a_{1i} \\ a_{2i} \\ \vdots \\ a_{mi} \end{bmatrix}$$

which is the coordinate matrix of $T(v_i)$ relative to the basis C for $i = 1, 2, \dots, n$.

Problems

- Let $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be a linear transformation defined by $T(x, y) = (x+y, 2x-y)$. Find the matrix for T relative to the bases $B = \{(1, 2), (-1, 1)\}$ and $C = \{(1, 0), (0, 1)\}$

Ans: Let $v_1 = (1, 2)$, $v_2 = (-1, 1)$ and $w_1 = (1, 0)$, $w_2 = (0, 1)$

By definition of T , $T(v_1) = T(1, 2) = (3, 0)$

$$\text{Let } (3, 0) = c_1 w_1 + c_2 w_2$$

$$\begin{aligned} &= c_1 (1, 0) + c_2 (0, 1) = (c_1, 0) + (0, c_2) \\ &= (c_1, c_2) \end{aligned}$$

$$\therefore c_1 = 3, c_2 = 0$$

$$\therefore T(v_1) = \cancel{3\omega_1} 3\omega_1 + 0\omega_2$$

$$\left[T(v_1) \right]_C = \begin{bmatrix} 3 \\ 0 \end{bmatrix}$$

$$T(v_2) = T(-1, 1) = (0, -3)$$

$$\begin{aligned} \text{Let } (0, -3) &= c_1 \omega_1 + c_2 \omega_2 \\ &= c_1 (1, 0) + c_2 (0, 1) \\ &= (c_1, 0) + (0, c_2) \\ &= (c_1, c_2) \end{aligned}$$

$$\therefore c_1 = 0, c_2 = -3$$

$$\therefore T(v_2) = 0\omega_1 - 3\omega_2$$

$$\left[T(v_2) \right]_C = \begin{bmatrix} 0 \\ -3 \end{bmatrix}$$

\therefore Matrix of T with respect to B and C is

$$\text{given by } \left[T \right]_B^C = \underline{\underline{\begin{bmatrix} 3 & 0 \\ 0 & -3 \end{bmatrix}}}$$

2. Let $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ be a linear transformation defined by $T(x, y, z) = (3x - 2z, 2y - z)$. Find the matrix for T relative to the bases $B = \{(1, 0, 1), (1, -1, 0), (0, 1, 1)\}$ and $C = \{(1, 1), (1, 0)\}$.

Ans: Let $v_1 = (1, 0, 1)$, $v_2 = (1, -1, 0)$, $v_3 = (0, 1, 1)$ and $\omega_1 = (1, 1)$, $\omega_2 = (1, 0)$

By definition of T , $T(v_1) = T(1, 0, 1) = (1, -1)$

$$\begin{aligned} \text{Let } (1, -1) &= c_1 \omega_1 + c_2 \omega_2 \\ &= c_1 (1, 1) + c_2 (1, 0) \\ &= (c_1, c_1) + (c_2, 0) = (c_1 + c_2, c_1) \end{aligned}$$

$$c_1 + c_2 = 1 \quad c_1 = -1$$

$$\therefore -1 + c_2 = 1 \Rightarrow c_2 = 1 + 1 = 2$$

$$\therefore T(v_1) = -1\omega_1 + 2\omega_2$$

$$\left[T(v_1) \right]_C = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$$

$$T(v_2) = T(1, -1, 0) = (3, -2)$$

$$\text{Let } (3, -2) = c_1\omega_1 + c_2\omega_2$$

$$= c_1(1, 1) + c_2(1, 0)$$

$$= (c_1, c_1) + (c_2, 0)$$

$$= (c_1 + c_2, c_1)$$

$$\therefore c_1 + c_2 = 3, \quad c_1 = -2$$

$$\therefore -2 + c_2 = 3 \Rightarrow c_2 = 3 + 2 = 5$$

$$\therefore T(v_2) = -2\omega_1 + 5\omega_2$$

$$\left[T(v_2) \right]_C = \begin{bmatrix} -2 \\ 5 \end{bmatrix}$$

$$T(v_3) = T(0, 1, 1) = (-2, 1)$$

$$\therefore c_1 + c_2 = -2, \quad c_1 = 1$$

$$\therefore 1 + c_2 = -2 \Rightarrow c_2 = -2 - 1 = -3$$

$$\therefore T(v_3) = 1\omega_1 - 3\omega_2$$

$$\left[T(v_3) \right]_C = \begin{bmatrix} 1 \\ -3 \end{bmatrix}$$

\therefore Matrix of T with respect to B and C is

$$\text{given by } \left[T \right]_B^C = \begin{bmatrix} -1 & -2 & 1 \\ 2 & 5 & -3 \end{bmatrix}$$

Note

Let T be a linear transformation from an n -dimensional vector space V into an m -dimensional vector space W and let $B = \{v_1, v_2, \dots, v_n\}$ be a basis for V and $C = \{w_1, w_2, \dots, w_m\}$ be a basis for W . Then

$$[T(v)]_C = [T]_B^C [v]_B.$$

3. For the linear transformation $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ defined by

$$T(x, y) = (x+y, 2x-y) \quad B = \{(1, 2), (-1, 1)\} \text{ and}$$

$C = \{(1, 0), (0, 1)\}$, use the matrix of T to find

$T(v)$ where $v = (5, 4)$.

Ans: Let $v_1 = (1, 2)$, $v_2 = (-1, 1)$ and $w_1 = (1, 0)$,
 $w_2 = (0, 1)$

$$T(v_1) = T(1, 2) = (3, 0)$$

$$\begin{aligned} (3, 0) &= c_1 w_1 + c_2 w_2 \\ &= c_1 (1, 0) + c_2 (0, 1) \\ &= (c_1, 0) + (0, c_2) \\ &= (c_1, c_2) \end{aligned}$$

$$\therefore c_1 = 3 \quad c_2 = 0$$

$$\text{So } T(v_1) = 3w_1 + 0w_2$$

$$[T(v_1)]_C = \begin{bmatrix} 3 \\ 0 \end{bmatrix}$$

$$T(v_2) = T(-1, 1) = (0, -3)$$

$$(0, -3) = c_1 w_1 + c_2 w_2$$

$$= c_1(1,0) + c_2(0,1)$$

$$= (c_1, 0) + (0, c_2)$$

$$= (c_1, c_2)$$

$$c_1 = 0, \quad c_2 = -3$$

$$\text{So } T(v_2) = 0w_1 - 3w_2$$

$$[T(v_2)]_C = \begin{bmatrix} 0 \\ -3 \end{bmatrix}$$

Matrix of T w.r.t. B and C is given by

$$[T]_B^C = \begin{bmatrix} 3 & 0 \\ 0 & -3 \end{bmatrix}$$

$$\text{Now } v = (5, 4)$$

$$(5, 4) = c_1 v_1 + c_2 v_2$$

$$= c_1(1, 2) + c_2(-1, 1)$$

$$= (c_1, 2c_1) + (-c_2, c_2)$$

$$= (c_1 - c_2, 2c_1 + c_2)$$

$$c_1 - c_2 = 5$$

$$2c_1 + c_2 = 4$$

$$c_1 = 3, \quad c_2 = -2$$

$$\therefore (5, 4) = 3v_1 - 2v_2$$

$$[v]_B = \begin{bmatrix} 3 \\ -2 \end{bmatrix}$$

$$[T(v)]_C = [T]_B^C [v]_B$$

$$= \begin{bmatrix} 3 & 0 \\ 0 & -3 \end{bmatrix} \begin{bmatrix} 3 \\ -2 \end{bmatrix} = \begin{bmatrix} 9 \\ 6 \end{bmatrix}$$

$$C = \{(1,0), (0,1)\} \therefore T(v) = 9(1,0) + 6(0,1)$$

$$\text{i.e. } T(5,4) = (9,0) + (0,6)$$

$$= \underline{\underline{(9,6)}}$$

4. Let $B = \{(-3,2), (4,-2)\}$ and $C = \{(-1,2), (2,-2)\}$ be the bases for \mathbb{R}^2 and let $\begin{bmatrix} -2 & 7 \\ -3 & 7 \end{bmatrix}$ be the matrix for $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ relative to B and C . Find $T(v)$, where $v = (11, -6)$.

Ans: $v_1 = (-3, 2), v_2 = (4, -2)$ and $w_1 = (-1, 2)$

$$w_2 = (2, -2)$$

$$v = (11, -6)$$

$$(11, -6) = c_1 v_1 + c_2 v_2$$

$$= c_1 (-3, 2) + c_2 (4, -2)$$

$$= (-3c_1, 2c_1) + (4c_2, -2c_2)$$

$$= (-3c_1 + 4c_2, 2c_1 - 2c_2)$$

$$\Rightarrow -3c_1 + 4c_2 = 11$$

$$2c_1 - 2c_2 = -6$$

$$\therefore c_1 = -1, c_2 = 2$$

$$\therefore (11, -6) = -1v_1 + 2v_2$$

$$[v]_B = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$$

$$[T(v)]_C = [T]_B^C [v]_B$$

$$= \begin{bmatrix} -2 & 7 \\ -3 & 7 \end{bmatrix} \begin{bmatrix} -1 \\ 2 \end{bmatrix} = \begin{bmatrix} 16 \\ 17 \end{bmatrix}$$

$$\text{Given that } C = \{(-1, 2), (2, -2)\}$$

$$\begin{aligned}\therefore T(v) &= 16(-1, 2) + 17(2, -2) \\ &= (-16, 32) + (34, -34) \\ &= (18, -2)\end{aligned}$$

$$\therefore T(11, -6) = \underline{\underline{(18, -2)}}$$

5. The matrix representation for $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is

$$[T]_B^B = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \text{ where } B = \{(1, 1), (2, 1)\}. \text{ Find } T(x, y)$$

Ans. Here B and C are same.

$$v_1 = w_1 = (1, 1), \quad v_2 = w_2 = (2, 1).$$

$$\begin{aligned}(x, y) &= c_1 v_1 + c_2 v_2 \\ &= c_1 (1, 1) + c_2 (2, 1) \\ &= (c_1, c_1) + (2c_2, c_2) \\ &= (c_1 + 2c_2, c_1 + c_2)\end{aligned}$$

$$\Rightarrow c_1 + 2c_2 = x$$

$$\underline{c_1 + c_2 = y}$$

$$c_2 = x - y$$

$$\therefore c_1 + (x - y) = y \Rightarrow c_1 = y - (x - y) = y - x + y = 2y - x$$

$$\therefore (x, y) = (2y - x)(1, 1) + (x - y)(2, 1).$$

$$\therefore [v]_B = \begin{bmatrix} 2y - x \\ x - y \end{bmatrix}$$

$$\text{New } [T(v)]_B = [T]_B^B [v]_B$$

$$= \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} 2y-x \\ x-y \end{bmatrix}$$

$$= \begin{bmatrix} 2y-x+2(x-y) \\ 3(2y-x)+4(x-y) \end{bmatrix}$$

$$= \begin{bmatrix} 2y-x+2x-2y \\ 6y-3x+4x-4y \end{bmatrix}$$

$$= \begin{bmatrix} x \\ x+2y \end{bmatrix}$$

$$\text{Given } B = \{(1, 1), (2, 1)\}$$

$$\therefore T(x, y) = x(1, 1) + (x+2y)(2, 1)$$

$$= (x, x) + (2(x+2y), x+2y)$$

$$= (x+2(x+2y), x+x+2y)$$

$$= (x+2x+4y, 2x+2y)$$

$$= (3x+4y, 2x+2y)$$